## **Physics 4062/5062 – Lecture Six – Atom Trapping Force**

**Outline**

Physical Principle of MOT – Review

Trapping Force – Doppler Shift and Zeeman Shift

Damped Motion and Spring Constant for Restoring Force

Polarization Gradient Cooling – Physical Picture

Review Physical Principle of MOT using  $J = 0 \rightarrow J' = 1$  transition

Derive Trapping Force in MOT

• Recall force due to absorption

$$
F_{\rm abs} = \left[\frac{\frac{I}{I_{\rm s}}}{1 + \frac{4\Delta^2}{\Gamma^2}}\right] \hbar k \Gamma \quad (14)
$$

 $Δ = ω - ω<sub>o</sub>$ 

- Recall that  $\Delta$  was corrected for Doppler shift
- Now, correct  $\Delta$  for Doppler shift and Zeeman shift
- Recall from Lecture One:

$$
\text{2eeman energy shift} = \mu \left(\frac{\text{dB}}{\text{dz}}\right) \mathbf{z} = \mu_{\text{B}} g_{\text{F}} m_{\text{F}} \left(\frac{\text{dB}}{\text{dz}}\right) \mathbf{z}
$$

$$
\text{C} \quad \text{Zeeman frequency shift} = \omega_z = \left(\frac{\mu}{h}\right) \left(\frac{dB}{dz}\right) = \left(\frac{\mu_B g_F m_F}{h}\right) \left(\frac{dB}{dz}\right) z = \beta z \text{ where } \beta = \left(\frac{\mu_B g_F m_F}{h}\right) \left(\frac{dB}{dz}\right)
$$
\n
$$
\text{F}_{\text{MOT}} = \text{F}_{+} + \text{F}_{-} = \left(\frac{1}{I_s}\right) \hbar k \left[\left(\frac{1}{1 + \left(\frac{4}{\Gamma^2}\right)[\Delta - kv - \beta z]^2}\right) - \left(\frac{1}{1 + \left(\frac{4}{\Gamma^2}\right)[\Delta + kv + \beta z]^2}\right)\right] \tag{32}
$$
\n
$$
\text{F}_{\text{MOT}} = 8 \left(\frac{1}{I_s}\right) \hbar k \left(\frac{\left[\frac{2\Delta}{\Gamma}\right][kv + \beta z]}{\left[1 + \left(\frac{2\Delta}{\Gamma}\right)^2\right]^2}\right) \tag{33}
$$

• Motion is damped harmonic; equation 33 is of the form

$$
F_{\text{mot}} = -\alpha v - \left(\frac{\alpha}{k}\right) \beta z = -\alpha v - k_{\text{spring}} z \qquad (34)
$$

• The spring constant  $k_s = \frac{a}{k}$  $\frac{\alpha}{\mathbf{k}}\beta$  (35) is proportional to dB/dz  $\omega_{\rm trap} = \sqrt{\frac{k_{\rm spring}}{M}}$ Matom **(36)**

Motion is described by equation for damped harmonic oscillator

$$
\ddot{z} + \alpha \dot{z} + \omega_{\text{trap}}^2 z = 0 \qquad (37)
$$

$$
\alpha = \frac{8\hbar k^2 \left(\frac{1}{I_S}\right) \left(\frac{2\Delta}{\Gamma}\right)}{M_{\text{atom}} \left[1 + \left(\frac{2\Delta}{\Gamma}\right)^2\right]^2}
$$

$$
\omega_{\rm trap}^2 = \frac{8\hbar k \left(\frac{I}{I_s}\right) \left(\frac{2\Delta}{\Gamma}\right) \beta}{M_{\rm atom} \left[1 + \left(\frac{2\Delta}{\Gamma}\right)^2\right]^2} \quad (38)
$$

• if  $\alpha^2/4\omega_{\text{trap}}^2 > 1 \implies$  overdamped motion

Motion is described by

$$
z=A\;exp[-k_st/\alpha]
$$

- $\alpha/k_{spring} \sim 1 \text{ms}$  for dB/dz ~ 10 G/cm (typical gradient)
- $\bullet$  estimate  $\omega_{trap}$
- estimate well depth